

Yonghao Zou

Email: yonghao.zou@epfl.ch Mob: (41) 76 276 93 46 Homepage: zouyonghao.github.io

RESEARCH INTEREST

Program Analysis, Verification, Network Protocols, Operating Systems, Distributed Systems

EDUCATION

EPFL (Advisor: Prof. George Candea) *Sep. 2024-Now*
Ph.D. Candidate in Computer Science
Research Topics: Program Verification, Software Interfaces, Operating Systems
Honor & Award: EDIC Fellowship

Tsinghua University (Advisor: Prof. Shi-Min Hu & Jia-Ju Bai) *Sep. 2019-Jun. 2022*
M.E. in Computer Technology
Main Courses: Computer System Performance Measurement, Advanced Operating Systems
Honor & Award: Outstanding Graduate, Tsinghua University

Zhejiang University *Sep. 2011-Jun. 2015*
B.E. in Computer Science and Technology

PUBLICATION

- [1] **Yong-Hao Zou**, Jia-Ju Bai, Jielong Zhou, Jianfeng Tan, Chenggang Qin, Shi-Min Hu. TCP-Fuzz: Detecting Memory and Semantic Bugs in TCP Stacks with Fuzzing. USENIX ATC, 2021.
- [2] **Yong-Hao Zou**, Jia-Ju Bai. Effective Crash Recovery of Robot Software Programs in ROS. ICRA, 2021.
- [3] Kai-Tao Xie, Jia-Ju Bai, **Yong-Hao Zou**, Yu-Ping Wang. ROZZ: Property-based Fuzzing for Robotic Programs in ROS. ICRA, 2022.
- [4] Can Cebeci, **Yonghao Zou**, Diyu Zhou, George Candea, Clément Pit-Claudel. Practical Verification of System-Software Components Written in Standard C. SOSP, 2024.

EXPERIENCE & RESEARCH

Work Experience: Software backend engineer in Shanghai, China
Software architecture group member in China Merchants Bank *Jul. 2015-Apr. 2018*

1. Develop a microservice framework, including configuration management systems, RPC framework, service management and discovery, and code generation tools.
2. Develop a message system for scale and availability, providing critical functions including at least once message delivery, high availability servers, server load balance, and manual message management.

Research Project: Research on Robot Operation System (ROS) reliability in Beijing, China
Project core member *Sep. 2019-Mar. 2020, May. 2021-Jul. 2021*

1. Develop a new lightweight recovery tool named RORY with checkpoint and message replay to recover ROS nodes effectively. RORY can recover six standard ROS programs in both virtual and realistic environments. (ICRA 20)
2. Develop a ROS fuzzing tool named ROZZ with three essential techniques, including a multi-dimensional generation method, a distributed branch coverage, and a temporal mutation strategy, to test ROS nodes effectively. ROZZ has successfully found 43 actual bugs on ten standard robotic programs in ROS 2. (ICRA 22)

Research Project: Research on reliability and correctness testing of TCP Stacks in Beijing, China
Project core member *Apr. 2020-Feb. 2021*

1. Develop a novel fuzzing framework, TCP-Fuzz, to effectively test TCP stacks and detect bugs using three essential techniques: a dependency-based generation strategy, a transition-guided fuzzing approach, and a differential checker. (ATC 21)
2. TCP-Fuzz is adapted to 5 TCP stacks and finds 56 bugs.

Research Project: Research on reliability and correctness testing of distributed systems in Beijing, China
Project leader *Mar. 2021-Now*

1. Propose a coverage-guided fuzzing approach using fault injection and different checkers to test distributed systems.
2. Develop a novel fuzzing framework that has found dozens of bugs in distributed systems. The framework can also find bugs in distributed relational databases after further extension.

Research Project: Research on a verification tool for systems and specifications written in C

in Lausanne, Switzerland

Project core member

Sep. 2023-Mar. 2024

1. Propose the use of a parallel CI pipeline to verify systems in parallel to improve the efficiency of verification.
2. Verify the correctness of Komodo written in C with the tool.

SKILLS

- System programming, including Linux driver development, scheduling, networking, distributed systems, and ROS
- Dynamic analysis based on LLVM
- Symbolic execution and verification tools
- Programming language: Java, C/C++, Python, SQL and Clojure